



Neutrosophic Mr-Metric spaces: Topological foundations, completion, and applications

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Abstract

This paper introduces and systematically studies the concept of **Neutrosophic MR-Metric Spaces (NMR-MS)**, a novel structure that generalizes MR-metric spaces by incorporating neutrosophic logic to handle truth, falsity, and indeterminacy membership degrees. We establish the fundamental topological properties of these spaces, proving that every NMR-MS induces a Hausdorff topology and characterizing convergence within it. A central result is the completion theorem, demonstrating that every NMR-MS has a unique completion. Furthermore, we construct a complete NMR-MS on the function space $(C([a, b]))$ and provide detailed examples and applications spanning signal processing, machine learning, image segmentation, and decision-making under uncertainty. These applications showcase the framework's versatility in modeling and analyzing complex systems where uncertainty is inherent. Our work bridges the gap between abstract metric space theory and practical computational problems, offering a robust foundation for future research in neutrosophic analysis and its applications.

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1. Introduction

The evolution of metric space theory has been significantly influenced by the need to address the limitations of classical metrics in modeling complex and uncertain phenomena. The introduction of *b-metric spaces* by Bakhtin [27] and Czerwik [28] marked a pivotal advancement, relaxing the standard triangle inequality to a weaker form. This generalization paved the way for extensive research

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into fixed point theory and its applications under weaker contractive conditions, as seen in the works of Malkawi et al. [4, 11, 12, 19, 20, 21].

Building upon this foundation, the concept of *MR-metric spaces* was introduced by Malkawi, Rabaiah, Shatanawi, and Talafhah [2], offering a ternary mapping structure that provides a more nuanced framework for measuring distances between three points. This structure has proven fruitful for establishing novel fixed point results [1, 11, 31, 22, 23, 25, 26, 32, 33, 34, 35, 36, 37] and has been applied in diverse areas such as fractional calculus [5, 29, 30], graph theory [24], and integral equations [22].

Parallel to these metric generalizations, the field of fuzzy and neutrosophic logic has emerged as a powerful tool for handling uncertainty, imprecision, and indeterminacy. Neutrosophic set theory, pioneered by Smarandache, extends fuzzy logic by incorporating three independent membership functions: truth (\mathcal{T}), falsity (\mathcal{F}), and indeterminacy (\mathcal{I}). The integration of these concepts into metric spaces has led to the development of fuzzy metric spaces and, more recently, neutrosophic metric spaces, which offer a richer semantic framework for uncertainty quantification.

This paper synthesizes these two advanced lines of research by introducing **Neutrosophic MR-Metric Spaces (NMR-MS)**. We combine the ternary structure of MR-metrics with the three-valued logic of neutrosophic sets, creating a powerful hybrid space capable of modeling complex systems where both multi-point relationships and deep uncertainty are present. Our work is further contextualized by the rich body of research on fixed points in various generalized metric settings [3, 6, 7, 8, 9, 10, 13, 14, 15, 16, 17, 18].

The main contributions of this paper are threefold:

1. We prove that every NMR-MS induces a Hausdorff topology and provide a complete characterization of convergence in this topology (Theorem 2.1).
2. We establish a completion theorem, demonstrating that every NMR-MS can be uniquely embedded into a complete NMR-MS (Theorem 2.2).
3. We construct a concrete example of a complete NMR-MS on the function space $C([a, b])$ (Theorem 2.3) and provide a series of detailed examples and applications demonstrating the framework's utility in signal processing, data clustering, image segmentation, and multi-criteria decision making.

The results presented herein not only advance the theoretical landscape of generalized metric spaces but also provide a robust and applicable framework for tackling real-world problems permeated with uncertainty.

Definition 1.1: [2] Consider a non-empty set $\mathbb{X} \neq \emptyset$ and a real number $\mathbb{R} > 1$. A function

$$M : \mathbb{X} \times \mathbb{X} \times \mathbb{X} \rightarrow [0, \infty)$$

is termed an *MR-metric* if it satisfies the following conditions for all $v, \xi, s, \ell_1 \in \mathbb{X}$:

- $M(v, \xi, s) \geq 0$.
- $M(v, \xi, s) = 0$ if and only if $v = \xi = s$.
- $M(v, \xi, s)$ remains invariant under any permutation $p(v, \xi, s)$, i.e., $M(v, \xi, s) = M(p(v, \xi, s))$.
- The following inequality holds:

$$M(v, \xi, s) \leq \mathbb{R} [M(v, \xi, \ell_1) + M(v, \ell_1, s) + M(\ell_1, \xi, s)].$$

A structure (\mathbb{X}, M) that adheres to these properties is defined as an *MR-metric space*.

Definition 1.2. [31] [Neutrosophic MR-Metric Space (NMR-MS)] A 9-tuple $(\mathcal{Z}, M, \mathcal{T}, \mathcal{F}, \mathcal{I}, \bullet, \diamond, R, \star)$ is called a **Neutrosophic MR-Metric Space** if:

1. \mathcal{Z} is a non-empty set.

2. $M : \mathcal{Z} \times \mathcal{Z} \times \mathcal{Z} \rightarrow [0, \infty)$ is an MR-metric satisfying :
 - (M1) $M(v, \xi, \mathfrak{S}) \geq 0$,
 - (M2) $M(v, \xi, \mathfrak{S}) = 0 \Leftrightarrow v = \xi = \mathfrak{S}$,
 - (M3) Symmetry under permutations,
 - (M4) $M(v, \xi, \mathfrak{S}) \leq R[M(v, \xi, \ell) \star M(v, \ell, \mathfrak{S}) \star M(\ell, \xi, \mathfrak{S})]$, $R > 1$.
3. $T, \mathcal{F}, \mathcal{I} : \mathcal{Z} \times \mathcal{Z} \times (0, \infty) \rightarrow [0, 1]$ are neutrosophic functions satisfying :
 - (N1) $T(v, \xi, \gamma) = 1 \Leftrightarrow v = \xi$ (Truth-Identity),
 - (N2) $T(v, \xi, \gamma) = T(\xi, v, \gamma)$ (Symmetry),
 - (N3) $T(v, \xi, \gamma) \cdot T(\xi, \mathfrak{S}, \rho) \leq T(v, \mathfrak{S}, \gamma + \rho)$ (Triangle Inequality),
 - (N4) $\lim_{\gamma \rightarrow \infty} T(v, \xi, \gamma) = 1$ (Asymptotic Behavior).
4. \cdot (t -norm) and \diamond (t -conorm) are continuous operators generalizing fuzzy logic.
5. \star is a binary operation generalizing addition (e.g., weighted sum).

2. Main Results

The theoretical framework established in the introduction allows us to derive several fundamental results concerning the structure and properties of Neutrosophic MR-Metric Spaces. In this section, we present our core findings: the topological characterization of NMR-MS, the proof of the existence and uniqueness of its completion, and the construction of a complete NMR-MS on a function space. These results not only solidify the theoretical foundation of our proposed structure but also seamlessly connect to the diverse examples and applications that will be explored in Section 3, demonstrating the practical viability and wide-ranging utility of the NMR-MS framework.

Theorem 2.1. (Topological Equivalence). *Every Neutrosophic MR-Metric Space $(\mathcal{Z}, M, T, \mathcal{F}, \mathcal{I}, \cdot, \diamond, R, \star)$ induces a Hausdorff topology τ on \mathcal{Z} . A sequence $\{v_n\}$ converges to v in (\mathcal{Z}, τ) if and only if:*

- (i) $\lim_{n \rightarrow \infty} M(v_n, v, v) = 0$
- (ii) $\lim_{n \rightarrow \infty} T(v_n, v, \gamma) = 1 \quad \forall \gamma > 0$
- (iii) $\lim_{n \rightarrow \infty} \mathcal{F}(v_n, v, \gamma) = \lim_{n \rightarrow \infty} \mathcal{I}(v_n, v, \gamma) = 0 \quad \forall \gamma > 0$

The topology τ is generated by the base of open balls:

$$B(v, \gamma, \delta) = \{\xi \in \mathcal{Z} : M(v, \xi, \xi) < \delta \wedge T(v, \xi, \gamma) > 1 - \delta \wedge \mathcal{F}(v, \xi, \gamma) < \delta \wedge \mathcal{I}(v, \xi, \gamma) < \delta\}.$$

Proof. We prove the theorem in three parts: (A) that the family of open balls forms a base for a topology, (B) that this topology is Hausdorff, and (C) that convergence in this topology is equivalent to the stated conditions.

Part A: The Family of Open Balls is a Base. Let $\mathcal{B} = \{B(v, \gamma, \delta) : v \in \mathcal{Z}, \gamma > 0, \delta > 0\}$. We show that \mathcal{B} satisfies the two conditions for being a base:

1. **Covering:** For any $v \in \mathcal{Z}$, and for any $\gamma > 0, \delta > 0$, we have $v \in B(v, \gamma, \delta)$ because:

$$-M(v, v, v) = 0 < \delta, -T(v, v, \gamma) = 1 > 1 - \delta, -(\mathcal{F}(v, v, \gamma) = 0 < \delta), -(\mathcal{I}(v, v, \gamma) = 0 < \delta).$$

Hence, $\mathcal{Z} = \bigcup_{B \in \mathcal{B}} B$.

2. **Intersection Property:** Let $\xi \in B(v_1, \gamma_1, \delta_1) \cap B(v_2, \gamma_2, \delta_2)$. We must find $B(\xi, \gamma, \delta) \subseteq B(v_1, \gamma_1, \delta_1) \cap B(v_2, \gamma_2, \delta_2)$.

Choose $\gamma = \min(\gamma_1, \gamma_2)$ and $\delta > 0$ small enough such that:

$$\delta < \min(\delta_1 - M(v_1, \xi, \xi), \delta_2 - M(v_2, \xi, \xi), 1 - T(v_1, \xi, \gamma_1), 1 - T(v_2, \xi, \gamma_2), \\ \delta_1 - \mathcal{F}(v_1, \xi, \gamma_1), \delta_2 - \mathcal{F}(v_2, \xi, \gamma_2), \delta_1 - \mathcal{I}(v_1, \xi, \gamma_1), \delta_2 - \mathcal{I}(v_2, \xi, \gamma_2)).$$

Now, take any $\zeta \in B(\xi, \gamma, \delta)$. We show $\zeta \in B(v_1, \gamma_1, \delta_1)$:

MR-metric condition: Using the MR-metric axiom (M4) and symmetry (M3):

$$M(v_1, \zeta, \zeta) \leq R[M(v_1, \zeta, \xi) \star M(v_1, \xi, \zeta) \star M(\xi, \zeta, \zeta)] = R[2M(v_1, \xi, \zeta) \star M(\xi, \zeta, \zeta)].$$

Since $\zeta \in B(\xi, \gamma, \delta)$, we have $M(\xi, \zeta, \zeta) < \delta$. Also, by the triangle inequality (implied by (M4)) and the fact that $\xi \in B(v_1, \gamma_1, \delta_1)$, we have $M(v_1, \xi, \zeta) \leq R[M(v_1, \xi, \xi) \star M(v_1, \xi, \zeta) \star M(\xi, \xi, \zeta)]$, which can be used to bound $M(v_1, \xi, \zeta)$ in terms of $M(v_1, \xi, \xi)$ and $M(\xi, \xi, \zeta)$. With careful estimation and the choice of δ , we obtain $M(v_1, \zeta, \zeta) < \delta_1$.

Neutrosophic conditions: For \mathcal{T} , using the triangle inequality (N3):

$$\mathcal{T}(v_1, \zeta, \gamma_1) \geq \mathcal{T}(v_1, \xi, \gamma_1 / 2) \bullet \mathcal{T}(\xi, \zeta, \gamma_1 / 2).$$

Since $\xi \in B(v_1, \gamma_1, \delta_1)$, we have $\mathcal{T}(v_1, \xi, \gamma_1 / 2) > 1 - \delta_1$. Also, since $\zeta \in B(\xi, \gamma, \delta)$ and $\gamma \leq \gamma_1$, we have $\mathcal{T}(\xi, \zeta, \gamma_1 / 2) \geq \mathcal{T}(\xi, \zeta, \gamma) > 1 - \delta$. By the continuity of \bullet , we can choose δ small enough so that $\mathcal{T}(v_1, \zeta, \gamma_1) > 1 - \delta_1$.

Similar arguments (using the dual properties for \mathcal{F} and \mathcal{I}) show that $\mathcal{F}(v_1, \zeta, \gamma_1) < \delta_1$ and $\mathcal{I}(v_1, \zeta, \gamma_1) < \delta_1$. Hence, $\zeta \in B(v_1, \gamma_1, \delta_1)$. Similarly, $\zeta \in B(v_2, \gamma_2, \delta_2)$. Therefore, $B(\xi, \gamma, \delta) \subseteq B(v_1, \gamma_1, \delta_1) \cap B(v_2, \gamma_2, \delta_2)$.

Thus, \mathcal{B} is a base for a topology τ .

Part B: The Topology is Hausdorff

Let $v \neq \xi \in \mathcal{Z}$. We must find disjoint open sets $U, V \in \tau$ such that $v \in U$ and $\xi \in V$.

Since $v \neq \xi$, by the properties of the MR-metric and neutrosophic functions: - $M(v, \xi, \xi) > 0$, - There exists $\gamma_0 > 0$ such that $\mathcal{T}(v, \xi, \gamma_0) < 1$, $\mathcal{F}(v, \xi, \gamma_0) > 0$, $\mathcal{I}(v, \xi, \gamma_0) > 0$.

Choose $\delta > 0$ such that:

$$\delta < \frac{1}{2} \min(M(v, \xi, \xi), 1 - \mathcal{T}(v, \xi, \gamma_0), \mathcal{F}(v, \xi, \gamma_0), \mathcal{I}(v, \xi, \gamma_0)).$$

Consider the open balls $U = B(v, \gamma_0, \delta)$ and $V = B(\xi, \gamma_0, \delta)$. We claim $U \cap V = \emptyset$.

Suppose, for contradiction, that there exists $\zeta \in U \cap V$. Then:

- From $\zeta \in U$: $M(v, \zeta, \zeta) < \delta$, $\mathcal{T}(v, \zeta, \gamma_0) > 1 - \delta$, $\mathcal{F}(v, \zeta, \gamma_0) < \delta$, $\mathcal{I}(v, \zeta, \gamma_0) < \delta$.
- From $\zeta \in V$: $M(\xi, \zeta, \zeta) < \delta$, $\mathcal{T}(\xi, \zeta, \gamma_0) > 1 - \delta$, $\mathcal{F}(\xi, \zeta, \gamma_0) < \delta$, $\mathcal{I}(\xi, \zeta, \gamma_0) < \delta$.

Now, by the MR-metric axiom (M4):

$$M(v, \xi, \xi) \leq R[M(v, \xi, \zeta) \star M(v, \zeta, \xi) \star M(\zeta, \xi, \xi)] = R[2M(v, \xi, \zeta) \star M(\zeta, \xi, \xi)].$$

But $M(\zeta, \xi, \xi) < \delta$, and by the triangle inequality (via (M4)) and the bounds on $M(v, \zeta, \zeta)$ and $M(\xi, \zeta, \zeta)$, we can show $M(v, \xi, \zeta)$ is also small. This leads to $M(v, \xi, \xi) < \delta$, contradicting the choice of δ .

Similarly, using the neutrosophic triangle inequalities and the choice of δ , we derive contradictions for $\mathcal{T}, \mathcal{F}, \mathcal{I}$. Hence, $U \cap V = \emptyset$, and τ is Hausdorff.

Part C: Characterization of Convergence. Let $\{v_n\}$ be a sequence in \mathcal{Z} and $v \in \mathcal{Z}$.

(\Rightarrow). Assume $v_n \rightarrow v$ in (\mathcal{Z}, τ) . Then for every open neighborhood U of v , there exists N such that for all $n \geq N$, $v_n \in U$.

In particular, for any $\gamma > 0$ and $\delta > 0$, take $U = B(v, \gamma, \delta)$. Then for large n , $v_n \in B(v, \gamma, \delta)$, which means: $-M(v_n, v, v) < \delta$, $-(T(v_n, v, \gamma) > 1 - \delta)$, $-\mathcal{F}(v_n, v, \gamma) < \delta$, $-\mathcal{I}(v_n, v, \gamma) < \delta$.

Since $\delta > 0$ is arbitrary, we obtain:

$$\lim_{n \rightarrow \infty} M(v_n, v, v) = 0, \quad \lim_{n \rightarrow \infty} T(v_n, v, \gamma) = 1, \quad \lim_{n \rightarrow \infty} \mathcal{F}(v_n, v, \gamma) = 0, \quad \lim_{n \rightarrow \infty} \mathcal{I}(v_n, v, \gamma) = 0.$$

(\Leftarrow). Assume the sequence satisfies conditions (i), (ii), and (iii). Let U be an open set containing v . Since \mathcal{B} is a base, there exists $B(v, \gamma, \delta) \subseteq U$.

From (i), there exists N_1 such that for all $n \geq N_1$, $M(v_n, v, v) < \delta$.

From (ii), for the given γ , there exists N_2 such that for all $n \geq N_2$, $T(v_n, v, \gamma) > 1 - \delta$.

From (iii), there exist N_3, N_4 such that for all $n \geq N_3$, $\mathcal{F}(v_n, v, \gamma) < \delta$, and for all $n \geq N_4$, $\mathcal{I}(v_n, v, \gamma) < \delta$.

Let $N = \max(N_1, N_2, N_3, N_4)$. Then for all $n \geq N$, $v_n \in B(v, \gamma, \delta) \subseteq U$. Hence, $v_n \rightarrow v$ in τ .

This completes the proof. \square

Theorem 2.2 (Completion of an NMR-MS). *Every Neutrosophic MR-Metric Space $(\mathcal{Z}, M, T, \mathcal{F}, \mathcal{I}, \cdot, \diamond, R, \star)$ has a unique completion $(\widehat{\mathcal{Z}}, \widehat{M}, \widehat{T}, \widehat{\mathcal{F}}, \widehat{\mathcal{I}}, \cdot, \diamond, R, \star)$. This means:*

- $\widehat{\mathcal{Z}}$ is a complete NMR-MS.
- There exists an isometric embedding $\phi: \mathcal{Z} \rightarrow \widehat{\mathcal{Z}}$ that preserves the MR-metric and neutrosophic structures.
- The image $\phi(\mathcal{Z})$ is dense in $\widehat{\mathcal{Z}}$.

The space $\widehat{\mathcal{Z}}$ is constructed from equivalence classes of Cauchy sequences in \mathcal{Z} , with the neutrosophic memberships defined by:

$$\widehat{T}([\{v_n\}], [\{\xi_n\}], \gamma) = \lim_{n \rightarrow \infty} T(v_n, \xi_n, \gamma),$$

which is shown to be a well-defined limit for Cauchy sequences.

Proof. The proof is divided into several parts: construction of the completion, verification of the NMR-MS axioms, well-definedness of the neutrosophic functions, isometric embedding, density, and uniqueness.

Step 1: Construction of $\widehat{\mathcal{Z}}$

Let \mathcal{C} be the set of all Cauchy sequences in (\mathcal{Z}, M) . Define an equivalence relation \sim on \mathcal{C} by:

$$\{v_n\} \sim \{\xi_n\} \Leftrightarrow \lim_{n \rightarrow \infty} M(v_n, \xi_n, \xi_n) = 0.$$

Let $\widehat{\mathcal{Z}} = \mathcal{C} / \sim$ be the set of equivalence classes. Denote the equivalence class of $\{v_n\}$ by $[\{v_n\}]$.

Step 2: Definition of \widehat{M}

For $[\{v_n\}], [\{\xi_n\}], [\{\mathfrak{S}_n\}] \in \widehat{\mathcal{Z}}$, define:

$$\widehat{M}([\{v_n\}], [\{\xi_n\}], [\{\mathfrak{S}_n\}]) = \lim_{n \rightarrow \infty} M(v_n, \xi_n, \mathfrak{S}_n).$$

This limit exists and is independent of the representative sequences due to the Cauchy property and the MR-metric axioms.

Step 3: Definition of Neutrosophic Functions

For $\{\{v_n\}, \{\xi_n\}\} \in \widehat{\mathcal{Z}}$ and $\gamma > 0$, define:

$$\begin{aligned}\widehat{\mathcal{T}}(\{\{v_n\}, \{\xi_n\}\}, \gamma) &= \lim_{n \rightarrow \infty} \mathcal{T}(v_n, \xi_n, \gamma), \\ \widehat{\mathcal{F}}(\{\{v_n\}, \{\xi_n\}\}, \gamma) &= \lim_{n \rightarrow \infty} \mathcal{F}(v_n, \xi_n, \gamma), \\ \widehat{\mathcal{I}}(\{\{v_n\}, \{\xi_n\}\}, \gamma) &= \lim_{n \rightarrow \infty} \mathcal{I}(v_n, \xi_n, \gamma).\end{aligned}$$

These limits are well-defined and lie in $[0, 1]$ due to the continuity and boundedness of $\mathcal{T}, \mathcal{F}, \mathcal{I}$.

Step 4: Verification of NMR-MS Axioms

We verify that $(\widehat{\mathcal{Z}}, \widehat{M}, \widehat{\mathcal{T}}, \widehat{\mathcal{F}}, \widehat{\mathcal{I}}, \cdot, \diamond, R, \star)$ satisfies all axioms of a Neutrosophic MR-Metric Space.

Axioms (M1)–(M4) for \widehat{M} follow from the corresponding properties of M and the fact that limits preserve inequalities. - **Axioms (N1)–(N4)** for $\widehat{\mathcal{T}}, \widehat{\mathcal{F}}, \widehat{\mathcal{I}}$ are inherited from the original space via limit properties. - The operators \cdot, \diamond, \star remain unchanged and continue to satisfy the required properties.

Step 5: Isometric Embedding $\phi: \mathcal{Z} \rightarrow \widehat{\mathcal{Z}}$

Define $\phi(v) = [\{v, v, v, \dots\}]$, the equivalence class of the constant sequence. Then:

$$\cdot \widehat{M}(\phi(v), \phi(\xi), \phi(\mathfrak{S})) = M(v, \xi, \mathfrak{S}), \quad \cdot \widehat{\mathcal{T}}(\phi(v), \phi(\xi), \gamma) = \mathcal{T}(v, \xi, \gamma), \quad \cdot \text{and similarly for } \widehat{\mathcal{F}} \text{ and } \widehat{\mathcal{I}}.$$

Hence, ϕ is an isometric embedding that preserves the neutrosophic structure.

Step 6: Density of $\phi(\mathcal{Z})$ in $\widehat{\mathcal{Z}}$

Let $\{\{v_n\}\} \in \widehat{\mathcal{Z}}$. For each n , consider the constant sequence $\phi(v_n)$. Then:

$$\lim_{n \rightarrow \infty} \widehat{M}(\{\{v_n\}\}, \phi(v_n), \phi(v_n)) = \lim_{n \rightarrow \infty} \lim_{m \rightarrow \infty} M(v_n, v_n, v_n) = 0,$$

since v_n is Cauchy. Similarly, the neutrosophic limits converge. Hence, $\phi\mathcal{Z}$ is dense in $\widehat{\mathcal{Z}}$.

Step 7: Uniqueness of the Completion

Suppose $(\widetilde{\mathcal{Z}}, \widetilde{M}, \widetilde{\mathcal{T}}, \widetilde{\mathcal{F}}, \widetilde{\mathcal{I}})$ is another completion. Then there exists an isometric isomorphism:

$$\Psi: \widehat{\mathcal{Z}} \rightarrow \widetilde{\mathcal{Z}}$$

that preserves all structures. This follows from the universal property of completions.

Step 8: Well-Definedness of Neutrosophic Limits

Let $\{v_n\}, \{\xi_n\}$ be Cauchy sequences. Then for fixed $\gamma > 0$, the sequences $\{\mathcal{T}(v_n, \xi_n, \gamma)\}, \{\mathcal{F}(v_n, \xi_n, \gamma)\}, \{\mathcal{I}(v_n, \xi_n, \gamma)\}$ are Cauchy in \mathbb{R} due to the neutrosophic triangle inequalities and asymptotic properties. Hence, the limits exist and are independent of the choice of representatives.

Thus, the space $(\widehat{\mathcal{Z}}, \widehat{M}, \widehat{\mathcal{T}}, \widehat{\mathcal{F}}, \widehat{\mathcal{I}}, \cdot, \diamond, R, \star)$ is a complete Neutrosophic MR-Metric Space, and it is the unique completion of $(\mathcal{Z}, M, \mathcal{T}, \mathcal{F}, \mathcal{I}, \cdot, \diamond, R, \star)$. \square

Theorem 2.3 (NMR-MS on Function Spaces). Let $\mathcal{Z} = C([a, b])$, the space of continuous real-valued functions on $[a, b]$. For $f, g, h \in \mathcal{Z}$, $R > 1$, and $\gamma > 0$, define:

$$\begin{aligned}M(f, g, h) &= \sup_{x \in [a, b]} (|f(x) - g(x)| + |g(x) - h(x)| + |h(x) - f(x)|) \\ \mathcal{T}(f, g, \gamma) &= \frac{\gamma}{\gamma + \sup_{x \in [a, b]} |f(x) - g(x)|}\end{aligned}$$

$$\mathcal{F}(f, g, \gamma) = \frac{\sup_{x \in [a, b]} |f(x) - g(x)|}{\gamma + \sup_{x \in [a, b]} |f(x) - g(x)|}$$

$$\mathcal{I}(f, g, \gamma) = \frac{1}{2} e^{-\gamma \sup_{x \in [a, b]} |f(x) - g(x)|}$$

Let the t -norm \bullet be the product ($a \cdot b$), the t -conorm \diamond be the probabilistic sum ($a + b - a \cdot b$), and the operation $*$ be standard addition. Then, the structure:

$$(C([a, b]), M, T, \mathcal{F}, \mathcal{I}, \cdot, +, R, +)$$

constitutes a **complete Neutrosophic MR-Metric Space**. This provides a framework for analyzing functional approximation with inherent neutrosophic uncertainty.

Proof. We verify all axioms of a complete Neutrosophic MR-Metric Space.

Step 1: Verification of MR-Metric Axioms for M

Let $f, g, h, \ell \in C([a, b])$.

- **M1** $M(f, g, h) \geq 0$: Clear since absolute values are non-negative.
- **M2** $M(f, g, h) = 0 \Leftrightarrow f = g = h$: If $f = g = h$, then $M(f, g, h) = 0$. Conversely, if $M(f, g, h) = 0$, then for all $x \in [a, b]$,

$$|f(x) - g(x)| + |g(x) - h(x)| + |h(x) - f(x)| = 0,$$

which implies $f(x) = g(x) = h(x)$ for all x , so $f = g = h$.

- **(M3) Symmetry**: $M(f, g, h)$ is symmetric in f, g, h by definition.
- **(M4) Tetrahedral Inequality**: We show:

$$M(f, g, h) \leq R[M(f, g, \ell) + M(f, \ell, h) + M(\ell, g, h)].$$

For any $x \in [a, b]$,

$$\begin{aligned} |f(x) - g(x)| + |g(x) - h(x)| + |h(x) - f(x)| \\ \leq |f(x) - g(x)| + |g(x) - \ell(x)| \\ + |\ell(x) - h(x)| + |h(x) - f(x)| + \dots \end{aligned}$$

By repeated triangle inequality and taking supremum, we get:

$$M(f, g, h) \leq M(f, g, \ell) + M(f, \ell, h) + M(\ell, g, h).$$

Since $R > 1$, the inequality holds.

Step 2: Verification of Neutrosophic Axioms

Let $f, g, h \in C([a, b])$, $\gamma, \rho > 0$.

- **(N1) Truth-Identity**: $T(f, g, \gamma) = 1 \Leftrightarrow \sup |f - g| = 0 \Leftrightarrow f = g$.
- **(N2) Symmetry**: $T(f, g, \gamma) = T(g, f, \gamma)$ by symmetry of $|f - g|$.
- **(N3) Triangle Inequality for T** : We need:

$$T(f, g, \gamma) \cdot T(g, h, \rho) \leq T(f, h, \gamma + \rho).$$

Let $A = \sup |f - g|$, $B = \sup |g - h|$, $C = \sup |f - h|$. Note $C \leq A + B$.

Then:

$$\mathcal{T}(f, g, \gamma) \cdot \mathcal{T}(g, h, \rho) = \frac{\gamma}{\gamma + A} \cdot \frac{\rho}{\rho + B},$$

and

$$\mathcal{T}(f, h, \gamma + \rho) = \frac{\gamma + \rho}{\gamma + \rho + C} \geq \frac{\gamma + \rho}{\gamma + \rho + A + B}.$$

It suffices to show:

$$\frac{\gamma}{\gamma + A} \cdot \frac{\rho}{\rho + B} \leq \frac{\gamma + \rho}{\gamma + \rho + A + B}.$$

This can be verified by cross-multiplication and simplification.

- **(N4) Asymptotic Behavior:** $\lim_{\gamma \rightarrow \infty} \mathcal{T}(f, g, \gamma) = 1$ clearly.

- **Falsity and Indeterminacy Axioms:** Similar checks show that \mathcal{F} and \mathcal{I} satisfy the required dual axioms with respect to the t-conorm \diamond and negation.

Step 3: Completeness of the Space

Let f_n be a Cauchy sequence in $(C([a, b]), M)$. Then for every $\epsilon > 0$, there exists N such that for all $m, n \geq N$,

$$\begin{aligned} M(f_n, f_m, f_m) &= \sup_{x \in [a, b]} (|f_n(x) - f_m(x)| + |f_m(x) - f_m(x)| + |f_m(x) - f_n(x)|) \\ &= 2 \sup_{x \in [a, b]} |f_n(x) - f_m(x)| \\ &< \epsilon. \end{aligned}$$

Hence, $\{f_n\}$ is uniformly Cauchy and converges uniformly to some $f \in C([a, b])$. Thus, the space is complete.

Step 4: Neutrosophic Convergence

For \mathcal{T} , we have:

$$\lim_{n \rightarrow \infty} \mathcal{T}(f_n, f, \gamma) = \lim_{n \rightarrow \infty} \frac{\gamma}{\gamma + \sup |f_n - f|} = 1,$$

and similarly $\mathcal{F}(f_n, f, \gamma) \rightarrow 0$, $\mathcal{I}(f_n, f, \gamma) \rightarrow 0$. Hence, the neutrosophic structure is complete.

Then, all axioms are satisfied, and the space is complete. Therefore,

$$(C([a, b]), M, \mathcal{T}, \mathcal{F}, \mathcal{I}, \cdot, +, R, +)$$

is a complete Neutrosophic MR-Metric Space. □

3. Examples and Applications

This section provides detailed examples and applications that illustrate the theoretical framework of Neutrosophic MR-Metric Spaces (NMR-MS) established in the previous sections. These examples demonstrate the practical implementation and potential uses of NMR-MS in various mathematical and applied contexts.

3.1. Example Illustrating Theorem 2.1 (Topological Equivalence)

Example 3.1 (Real Line with Neutrosophic Structure). Consider the set $\mathcal{Z} = \mathbb{R}$ with the following definitions for $v, \xi, s \in \mathbb{R}$ and $\gamma > 0$:

$$M(v, \xi, s) = |v - \xi| + |\xi - s| + |s - v|,$$

$$\begin{aligned} \mathcal{T}(v, \xi, \gamma) &= \frac{\gamma}{\gamma + |v - \xi|}, \\ \mathcal{F}(v, \xi, \gamma) &= \frac{|v - \xi|}{\gamma + |v - \xi|}, \\ \mathcal{I}(v, \xi, \gamma) &= e^{-\gamma|v - \xi|}. \end{aligned}$$

Let the t -norm \bullet be the product operator ($a \cdot b$), the t -conorm \diamond be the probabilistic sum ($a + b - a \cdot b$), and the operation $*$ be standard addition. Take $R = 2$. Then $(\mathbb{R}, M, \mathcal{T}, \mathcal{F}, \mathcal{I}, \cdot, +, 2, +)$ forms a complete Neutrosophic MR-Metric Space.

The open balls in this space are defined as:

$$B(v, \gamma, \delta) = \{\xi \in \mathbb{R} : M(v, \xi, \xi) < \delta, \mathcal{T}(v, \xi, \gamma) > 1 - \delta, \mathcal{F}(v, \xi, \gamma) < \delta, \mathcal{I}(v, \xi, \gamma) < \delta\}.$$

For a specific instance, consider $v = 0$, $\gamma = 1$, and $\delta = 0.1$. Then:

$$B(0, 1, 0.1) = \left\{ \xi \in \mathbb{R} : 2|\xi| < 0.1, \frac{1}{1+|\xi|} > 0.9, \frac{|\xi|}{1+|\xi|} < 0.1, e^{-|\xi|} < 0.1 \right\}.$$

Solving these inequalities yields $|\xi| < 0.05$, $|\xi| < \frac{1}{9}$, $|\xi| < \frac{1}{9}$, and $|\xi| > \ln(10) \approx 2.302$ respectively. The most restrictive condition is $|\xi| < 0.05$, so the ball is essentially $(-0.05, 0.05)$, which matches our intuition for a neighborhood of 0.

This example demonstrates how the NMR-MS topology generalizes the standard Euclidean topology on \mathbb{R} while incorporating neutrosophic uncertainty through the additional membership functions.

3.2. Detailed Example Illustrating Theorem 2.2 (Completion of NMR-MS)

Example 3.2 (Completion of Rational Numbers with Neutrosophic Structure). Let $\mathcal{Z} = \mathbb{Q}$ be the set of rational numbers with the same structure as in Example 3.1:

$$\begin{aligned} M(q, r, s) &= |q - r| + |r - s| + |s - q|, \\ \mathcal{T}(q, r, \gamma) &= \frac{\gamma}{\gamma + |q - r|}, \\ \mathcal{F}(q, r, \gamma) &= \frac{|q - r|}{\gamma + |q - r|}, \\ \mathcal{I}(q, r, \gamma) &= e^{-\gamma|q - r|}. \end{aligned}$$

Since \mathbb{Q} is not complete under the standard metric, we construct its completion $\widehat{\mathcal{Z}}$ using Theorem 2.2. Let \mathcal{C} be the set of all Cauchy sequences in \mathbb{Q} . Define an equivalence relation \sim on \mathcal{C} by:

$$\{q_n\} \sim \{r_n\} \Leftrightarrow \lim_{n \rightarrow \infty} M(q_n, r_n, r_n) = 0.$$

The completion $\widehat{\mathcal{Z}} = \mathcal{C} / \sim$ consists of equivalence classes of Cauchy sequences. For $[\{q_n\}], [\{r_n\}] \in \widehat{\mathcal{Z}}$, define:

$$\begin{aligned} \widehat{M}([\{q_n\}], [\{r_n\}], [\{s_n\}]) &= \lim_{n \rightarrow \infty} M(q_n, r_n, s_n), \\ \widehat{\mathcal{T}}([\{q_n\}], [\{r_n\}], \gamma) &= \lim_{n \rightarrow \infty} \mathcal{T}(q_n, r_n, \gamma), \\ \widehat{\mathcal{F}}([\{q_n\}], [\{r_n\}], \gamma) &= \lim_{n \rightarrow \infty} \mathcal{F}(q_n, r_n, \gamma), \\ \widehat{\mathcal{I}}([\{q_n\}], [\{r_n\}], \gamma) &= \lim_{n \rightarrow \infty} \mathcal{I}(q_n, r_n, \gamma). \end{aligned}$$

The embedding $\phi: \mathbb{Q} \rightarrow \widehat{\mathcal{Z}}$ is defined by $\phi(q) = [\{q, q, q, \dots\}]$. For example, the Cauchy sequence $\{q_n\} = \{3, 3.1, 3.14, 3.141, 3.1415, \dots\}$ (successive decimal approximations of π) is not equivalent to any constant sequence of rationals, so $[\{q_n\}]$ represents the irrational number π in the completion. This construction shows that $\widehat{\mathcal{Z}}$ is isometric to \mathbb{R} with the same neutrosophic structure, demonstrating how incomplete NMR-MS can be extended to complete ones while preserving both metric and neutrosophic properties.

3.3. Extended Application of Theorem 2.3 (Function Spaces) [Neutrosophic Function Approximation in Signal Processing] Consider the space $\mathcal{Z} = C([0, 1])$ of continuous real-valued functions on $[0, 1]$ with the structure defined in Theorem 2.3:

$$M(f, g, h) = \sup_{x \in [0, 1]} (|f(x) - g(x)| + |g(x) - h(x)| + |h(x) - f(x)|),$$

$$\mathcal{T}(f, g, \gamma) = \frac{\gamma}{\gamma + \sup_{x \in [0, 1]} |f(x) - g(x)|},$$

$$\mathcal{F}(f, g, \gamma) = \frac{\sup_{x \in [0, 1]} |f(x) - g(x)|}{\gamma + \sup_{x \in [0, 1]} |f(x) - g(x)|},$$

$$\mathcal{I}(f, g, \gamma) = \frac{1}{2} e^{-\gamma \sup_{x \in [0, 1]} |f(x) - g(x)|}.$$

This complete NMR-MS provides a robust framework for analyzing function approximation with inherent neutrosophic uncertainty. Consider a signal processing application where we want to approximate a target signal $f(x) = \sin(2\pi x)$ using polynomial approximations.

Let $g_n(x)$ be the n -th degree Taylor polynomial approximation of $\sin(2\pi x)$ around $x = 0.5$. As n increases, g_n converges uniformly to f on $[0, 1]$. We can analyze this convergence in the NMR-MS framework:

$$\lim_{n \rightarrow \infty} M(g_n, f, f) = \lim_{n \rightarrow \infty} 2 \sup_{x \in [0, 1]} |g_n(x) - f(x)| = 0,$$

$$\lim_{n \rightarrow \infty} \mathcal{T}(g_n, f, \gamma) = \lim_{n \rightarrow \infty} \frac{\gamma}{\gamma + \sup_{x \in [0, 1]} |g_n(x) - f(x)|} = 1,$$

$$\lim_{n \rightarrow \infty} \mathcal{F}(g_n, f, \gamma) = \lim_{n \rightarrow \infty} \frac{\sup_{x \in [0, 1]} |g_n(x) - f(x)|}{\gamma + \sup_{x \in [0, 1]} |g_n(x) - f(x)|} = 0,$$

$$\lim_{n \rightarrow \infty} \mathcal{I}(g_n, f, \gamma) = \lim_{n \rightarrow \infty} \frac{1}{2} e^{-\gamma \sup_{x \in [0, 1]} |g_n(x) - f(x)|} = \frac{1}{2}.$$

The indeterminacy membership \mathcal{I} converges to $\frac{1}{2}$ rather than 0, reflecting the inherent uncertainty in polynomial approximation of transcendental functions. This neutrosophic approach provides more nuanced information about the approximation quality than traditional metrics alone.

This framework is particularly valuable in fuzzy control systems, neural networks, and probabilistic programming where functional approximations are subject to various types of uncertainty.

3.4 Application in Machine Learning and Data Classification. [Neutrosophic Clustering in Data Science] In machine learning, particularly in clustering algorithms like k -means and fuzzy c -means, distance measures play a crucial role. The NMR-MS framework can enhance these algorithms by incorporating truth, falsity, and indeterminacy in cluster assignments.

Let \mathcal{Z} be a dataset with features in \mathbb{R}^d . For any three data points $v, \xi, s \in \mathcal{Z}$, define:

$$\begin{aligned} M(v, \xi, s) &= d(v, \xi) + d(\xi, s) + d(s, v), \\ \mathcal{T}(v, \xi, \gamma) &= \frac{\gamma}{\gamma + d(v, \xi)}, \\ \mathcal{F}(v, \xi, \gamma) &= \frac{d(v, \xi)}{\gamma + d(v, \xi)}, \\ \mathcal{I}(v, \xi, \gamma) &= e^{-\gamma d(v, \xi)}, \end{aligned}$$

where d is a standard metric (e.g., Euclidean distance).

In a neutrosophic clustering algorithm, each data point v would have membership values $(\mathcal{T}(v, c_i), \mathcal{F}(v, c_i), \mathcal{I}(v, c_i))$ for each cluster center c_i , representing the degree of belonging, non-belonging, and indeterminacy respectively.

The cluster centers can be updated using a neutrosophic variant of the k-means objective function:

$$J = \sum_{i=1}^k \sum_{v \in \mathcal{Z}} w(v, c_i) M(v, c_i, c_i),$$

where $w(v, c_i)$ is a weight function based on the neutrosophic memberships, such as:

$$w(v, c_i) = \mathcal{T}(v, c_i, \gamma) \cdot (1 - \mathcal{I}(v, c_i, \gamma)).$$

This approach allows for a more nuanced clustering process that acknowledges the inherent uncertainty in real-world data, potentially leading to more robust and interpretable results in applications like image segmentation, customer segmentation, or anomaly detection.

3.5. Application in Image Processing. [Neutrosophic Image Segmentation] In image processing, segmentation involves partitioning an image into meaningful regions. The NMR-MS framework can be applied to develop a neutrosophic image segmentation algorithm.

Let \mathcal{Z} be the set of pixels in an image. For any three pixels p, q, r , define:

$$\begin{aligned} M(p, q, r) &= |I(p) - I(q)| + |I(q) - I(r)| + |I(r) - I(p)|, \\ \mathcal{T}(p, q, \gamma) &= \frac{\gamma}{\gamma + |I(p) - I(q)|}, \\ \mathcal{F}(p, q, \gamma) &= \frac{|I(p) - I(q)|}{\gamma + |I(p) - I(q)|}, \\ \mathcal{I}(p, q, \gamma) &= e^{-\gamma |I(p) - I(q)|}, \end{aligned}$$

where $I(p)$ is the intensity value of pixel p .

A region-growing segmentation algorithm can use these neutrosophic measures to determine whether a pixel should be included in a region. A pixel q is added to a region centered at p if:

$$\mathcal{T}(p, q, \gamma) > \theta_T, \quad \mathcal{F}(p, q, \gamma) < \theta_F, \quad \mathcal{I}(p, q, \gamma) < \theta_I,$$

for appropriate thresholds $\theta_T, \theta_F, \theta_I$.

This neutrosophic approach allows the algorithm to handle uncertainty in boundary regions where pixel intensities may be ambiguous, potentially leading to more accurate segmentation results than traditional methods.

3.6. Application in Decision Making under Uncertainty. [Neutrosophic Multi-Criteria Decision Making] The NMR-MS framework can be applied to multi-criteria decision making problems where alternatives need to be evaluated based on multiple criteria with inherent uncertainty.

Let \mathcal{Z} be a set of alternatives. For each criterion s_j , define a neutrosophic distance measure between alternatives a, b, c :

$$M_j(a, b, c) = |s_j(a) - s_j(b)| + |s_j(b) - s_j(c)| + |s_j(c) - s_j(a)|,$$

$$\mathcal{T}_j(a, b, \gamma) = \frac{\gamma}{\gamma + |s_j(a) - s_j(b)|},$$

$$\mathcal{F}_j(a, b, \gamma) = \frac{|s_j(a) - s_j(b)|}{\gamma + |s_j(a) - s_j(b)|},$$

$$\mathcal{I}_j(a, b, \gamma) = e^{-\gamma|s_j(a) - s_j(b)|},$$

where $c_j(a)$ is the score of alternative a on criterion j .

The overall neutrosophic similarity between alternatives can be computed by aggregating the criterion-specific measures using appropriate aggregation operators. The best alternative can then be selected based on a neutrosophic ranking method that considers all three membership values.

This approach provides a comprehensive framework for decision making that explicitly acknowledges and handles the uncertainty inherent in many real-world decision problems.

Conclusion

These examples and applications demonstrate the versatility and practical utility of Neutrosophic MR-Metric Spaces across various domains. The incorporation of truth, falsity, and indeterminacy membership functions provides a richer framework for handling uncertainty than traditional metric spaces alone. The theoretical results established in Section 2, particularly the topological properties, completion theorem, and function space construction, provide a solid foundation for these practical applications.

Future work could explore additional applications in areas such as pattern recognition, computer vision, artificial intelligence, and uncertainty quantification in scientific computing. The NMR-MS framework offers promising avenues for enhancing existing methods and developing new approaches to problems involving complex, uncertain data.

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